

Interaction of clines under the prism of generalized travelling waves

Benoît Sarels

Sorbonne Université, Laboratoire Jacques-Louis Lions



Nonlinear waves and networks

INSA Rouen

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Population genetics systems with genetic incompatibilities

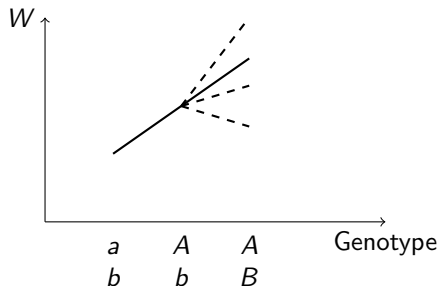
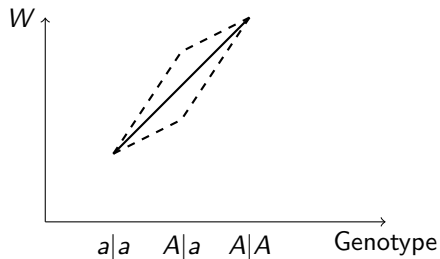


Joint work with : Matthieu Alfaro (Université de Rouen)

Quentin Griette (Université de Bordeaux)

Denis Roze (Marine Station Roscoff, CNRS).

- ▶ Genetic incompatibilities = non-linear interactions
- ▶ Dominance, epistasis



Population genetics equations and their solutions

Case study: two underdominant loci in diploid individuals

- Model establishment

- Numerical simulations

- Generalized travelling waves

Opening: N underdominant loci in diploid individuals

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Opening: N underdominant loci in diploid individuals

One locus, two alleles I

- ▶ Population in a linear habitat
- ▶ Diploid individuals
- ▶ Life cycle
 1. Random fusion of gametes → birth of new individuals
 2. Production of gametes (according to fitness)
 3. Migration of gametes
- ▶ p frequency of allele A
 $1 - p$ frequency of allele a
- ▶ W_{aa} , W_{Aa} , W_{AA} fitnesses of individuals

$$W_{aa} = 1$$

$$W_{Aa} = 1 + s_A$$

$$W_{AA} = 1 + 2s_A$$

with $0 \leq s_A$

$$W_{aa} = 1$$

$$W_{Aa} = 1 + s_A - S_A$$

$$W_{AA} = 1 + 2s_A$$

with $0 \leq s_A < S_A$ (**underdominance**)

One locus, two alleles II

1. Random fusion of gametes \rightarrow birth of new individuals
 p^2 frequency of individuals AA , $(1 - p)^2$ frequency of individuals aa ,
 $2p(1 - p)$ frequency of individuals Aa
2. Production of gametes (according to fitness)

$$p' = \frac{(1 + s_A)p(1 - p) + (1 + 2s_A)p^2}{(1 - p)^2 + 2(1 + s_A)p(1 - p) + (1 + 2s_A)p^2} \quad \text{or}$$
$$p' = \frac{(1 + s_A - S_A)p(1 - p) + (1 + 2s_A)p^2}{(1 - p)^2 + 2(1 + s_A - S_A)p(1 - p) + (1 + 2s_A)p^2}$$

3. Migration of gametes

$$p''(x) = \int_{-\infty}^{+\infty} p'(x - \delta x) f(\delta x) d(\delta x)$$

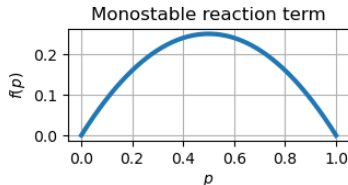
where f has mean 0 and variance σ^2

- Discrete time process approximated through a continuous time process \rightarrow equation on $p(x, t)$

Reaction-diffusion equations

Suppose $s_A \ll 1$, we get

$$\partial_t p = s_A p(1-p) + \frac{\sigma^2}{2} \partial_{xx}^2 p$$

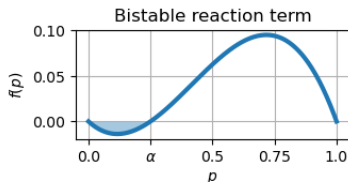


Suppose $s_A, S_A \ll 1$, we get

$$\partial_t p = \left(s_A + S_A(2p - 1) \right) p(1-p) + \frac{\sigma^2}{2} \partial_{xx}^2 p$$

$$\partial_t p = 2S_A p(p - \alpha)(1-p) + \frac{\sigma^2}{2} \partial_{xx}^2 p$$

where $\alpha = \frac{S_A - s_A}{2S_A} > 0$



What do those equations have in common? What solutions are expected?

Their basic properties: common points

The monostable and the bistable equation have **travelling wave** solutions.

- Write the equation in abstract form

$$\partial_t p = f(p) + \partial_{xx}^2 p$$

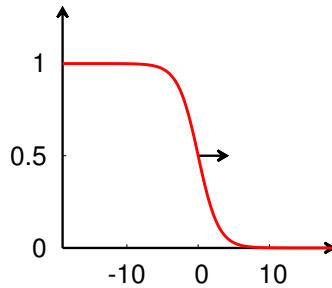
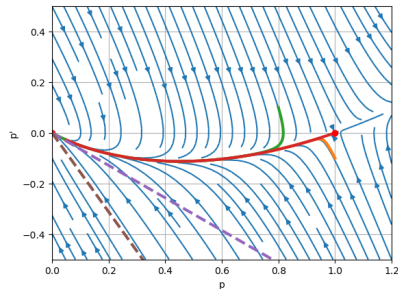
- Travelling wave

$$p(x, t) = \tilde{p}(z) \quad \text{with} \quad z = x - ct$$

- We search a couple (c, \tilde{p}) such that

$$-c\tilde{p}' = f(p) + \tilde{p}''$$

- **Propagation** of advantageous allele A



Their basic properties: differences

Monostable equation (logistic reaction term)

$$\partial_t p = s_A p(1 - p) + \frac{\sigma^2}{2} \partial_{xx}^2 p$$

- ▶ **Continuum** of possible speeds $c \geq 2\sigma\sqrt{s_A}$
- ▶ Fixed profile for a given speed
- ▶ No explicit solutions except (Ablowitz, 1978)

$$\tilde{p}(z) = \frac{1}{(1 + \exp(z))^2}$$

for the speed $c = \frac{5}{\sqrt{6}}\sigma\sqrt{s_A}$

Bistable equation (cubic reaction term)

$$\partial_t p = 2S_A p(p - \alpha)(1 - p) + \frac{\sigma^2}{2} \partial_{xx}^2 p$$

- ▶ Unique speed $c = \frac{\sigma s_A}{\sqrt{S_A}}$
- ▶ Fixed profile
- ▶ Given explicitly by (Barton, 1979)

$$\tilde{p}(z) = \frac{1}{1 + \exp(z)}$$

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One more locus adds a layer of complexity

- ▶ Two loci, two alleles (same hypotheses as before)
 $q(x, t)$ frequency of allele B
 $1 - q(x, t)$ frequency of allele b
- ▶ W_{bb}, W_{Bb}, W_{BB} fitnesses of individuals

$$W_{bb} = 1$$

$$W_{Bb} = 1 + s_B - S_B$$

$$W_{BB} = 1 + 2s_B$$

with $s_B \geq 0$ and $S_B > s_B$

- ▶ $W_{x,y} = W_x W_y$

Two loci, two alleles I

- Possibility of recombination events during meiosis (recombination rate $0 < r \leq \frac{1}{2}$)

- Individual $\begin{smallmatrix} A \\ B \end{smallmatrix} \bigg| \begin{smallmatrix} a \\ b \end{smallmatrix}$ yields:

1. $\begin{smallmatrix} A \\ B \end{smallmatrix}$ in proportion $\frac{1-r}{2}$

2. $\begin{smallmatrix} a \\ b \end{smallmatrix}$ in proportion $\frac{1-r}{2}$

3. $\begin{smallmatrix} A \\ b \end{smallmatrix}$ in proportion $\frac{r}{2}$

4. $\begin{smallmatrix} a \\ B \end{smallmatrix}$ in proportion $\frac{r}{2}$

- y_1, y_2, y_3, y_4 frequencies of gametes AB, Ab, aB, ab (resp.)

1. Random fusion of gametes \rightarrow birth of new individuals

$z_{i,j}$ frequency of diploid individuals obtained through fusion of gametes i et j :

$$z_{i,j} = \begin{cases} 2y_i y_j & \text{if } i \neq j \\ y_i^2 & \text{if } i = j \end{cases}$$

Two loci, two alleles II

2. Production of gametes (according to fitness)

$$z'_{i,j} = \frac{W_{i,j}z_{i,j}}{\bar{W}}$$

where $\bar{W} = \sum_{i,j} W_{i,j}z_{i,j}$.

We get

$$\begin{cases} y'_1 = z'_{1,1} + \frac{1}{2}(z'_{1,2} + z'_{1,3} + (1-r)z'_{1,4} + rz'_{2,3}) \\ y'_2 = z'_{2,2} + \frac{1}{2}(z'_{2,1} + z'_{2,4} + (1-r)z'_{2,3} + rz'_{1,4}) \\ y'_3 = z'_{3,3} + \frac{1}{2}(z'_{3,1} + z'_{3,4} + (1-r)z'_{3,2} + rz'_{1,4}) \\ y'_4 = z'_{4,4} + \frac{1}{2}(z'_{4,2} + z'_{4,3} + (1-r)z'_{4,1} + rz'_{2,3}) \end{cases}$$

Two loci, two alleles III

3. Migration of gametes

$$y''(x) = \int_{-\infty}^{+\infty} y'(x - \delta x) f(\delta x) d(\delta x)$$

where f has mean 0 and variance σ^2

Evolution system

- Suppose $S_A, S_B, r \ll 1$, we get

$$\begin{cases} \frac{dy_1}{dt} = f_1(y) := y_1 P_1(y) + r(y_2 y_3 - y_1 y_4) \\ \frac{dy_2}{dt} = f_2(y) := y_2 P_2(y) + r(y_1 y_4 - y_2 y_3) \\ \frac{dy_3}{dt} = f_3(y) := y_3 P_3(y) + r(y_1 y_4 - y_2 y_3) \\ \frac{dy_4}{dt} = f_4(y) := y_4 P_4(y) + r(y_2 y_3 - y_1 y_4) \end{cases}$$

- Change of variables $p = y_1 + y_2$ frequency of allele A, $q = y_1 + y_3$ frequency of allele B, and $D = y_1 y_4 - y_2 y_3$ linkage disequilibrium, gives

$$\begin{cases} \frac{dp}{dt} = 2S_A p(p - \alpha)(1 - p) + 2S_B (q - \beta)D \\ \frac{dq}{dt} = 2S_B q(q - \beta)(1 - q) + 2S_A (p - \alpha)D \\ \frac{dD}{dt} = -D \left(r + 4S_A(p - \alpha)(p - \frac{1}{2}) + 4S_B(q - \beta)(q - \frac{1}{2}) \right) \end{cases}$$

with $\alpha = (S_A - s_A)/2S_A$ and $\beta = (S_B - s_B)/2S_B$.

Reaction-diffusion system

Taking migration into account

$$\partial_t y_i = f_i(y) + \partial_{xx}^2 y_i$$

we get

$$\begin{cases} \partial_t p = f_1(y) + \partial_{xx}^2 y_1 + f_2(y) + \partial_{xx}^2 y_2 \\ \partial_t q = f_1(y) + \partial_{xx}^2 y_1 + f_3(y) + \partial_{xx}^2 y_3 \\ \partial_t D = y_1 f_4(y) + y_1 \partial_{xx}^2 y_4 + y_4 f_1(y) + y_4 \partial_{xx}^2 y_1 - y_2 f_3(y) - y_2 \partial_{xx}^2 y_3 - y_3 f_2(y) - y_3 \partial_{xx}^2 y_2 \end{cases}$$

Then

$$\begin{aligned} y_1 \partial_{xx}^2 y_4 + y_4 \partial_{xx}^2 y_1 - y_2 \partial_{xx}^2 y_3 - y_3 \partial_{xx}^2 y_2 &= \partial_{xx}^2 D - (2\partial_x y_1 \partial_x y_4 - 2\partial_x y_2 \partial_x y_3) \\ &= \partial_{xx}^2 D + 2\partial_x p \partial_x q \end{aligned}$$

$$\begin{cases} \partial_t p = 2S_A p(p - \alpha)(1 - p) + 2S_B (q - \beta)D + \partial_{xx}^2 p \\ \partial_t q = 2S_B q(q - \beta)(1 - q) + 2S_A (p - \alpha)D + \partial_{xx}^2 q \\ \partial_t D = -D \left(r + 4S_A (p - \alpha) \left(p - \frac{1}{2} \right) + 4S_B (q - \beta) \left(q - \frac{1}{2} \right) \right) + 2\partial_x p \partial_x q + \partial_{xx}^2 D \\ p(\cdot, 0) = p_0(x) \quad q(\cdot, 0) = q_0(x) \quad D(\cdot, 0) = 0 \end{cases} \quad (\star_{p,q,D})$$

Population genetics equations and their solutions

Case study: two underdominant loci in diploid individuals

Model establishment

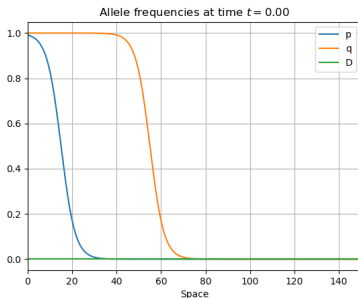
Numerical simulations

Generalized travelling waves

Opening: N underdominant loci in diploid individuals

Simulation #1: travelling waves ?

Same direction, same speed



$$s_A = 0.08,$$

$$S_A = 0.1,$$

$$c_p = \frac{s_A}{\sqrt{S_A}} = 0.25$$

$$s_B = 0.08,$$

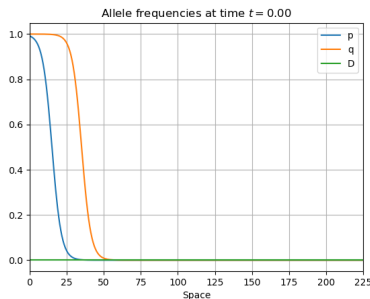
$$S_B = 0.1,$$

$$c_q = \frac{s_B}{\sqrt{S_B}} = 0.25$$

$$r = 0.01$$

Simulation #2: beware of the initial condition!

Same direction, same speed



$$s_A = 0.08,$$

$$S_A = 0.1,$$

$$c_p = \frac{s_A}{\sqrt{S_A}} = 0.25$$

$$s_B = 0.08,$$

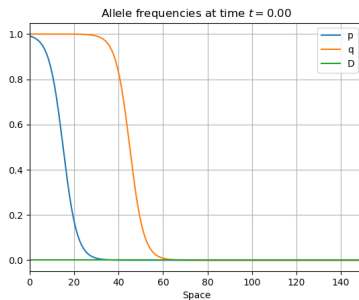
$$S_B = 0.1,$$

$$c_q = \frac{s_B}{\sqrt{S_B}} = 0.25$$

$$r = 0.01$$

Simulation #3

Same direction, speed discrepancy



$$s_A = 0.08,$$

$$S_A = 0.1,$$

$$c_p = \frac{s_A}{\sqrt{S_A}} = 0.25$$

$$s_B = 0,$$

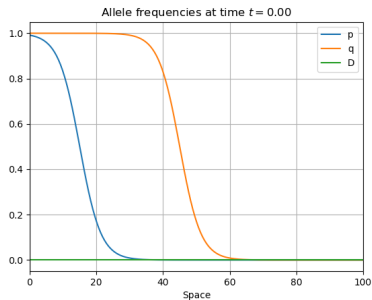
$$S_B = 0.1,$$

$$c_q = \frac{s_B}{\sqrt{S_B}} = 0$$

$$r = 0.01$$

Simulation #4

Same direction, (smaller) speed discrepancy



$$s_A = 0.04,$$

$$S_A = 0.1,$$

$$c_p = \frac{s_A}{\sqrt{S_A}} = 0.13$$

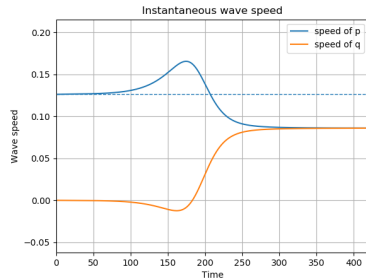
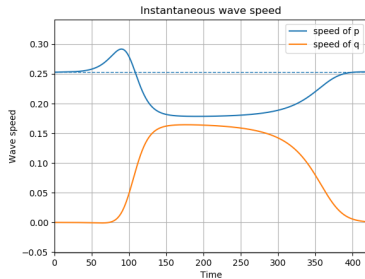
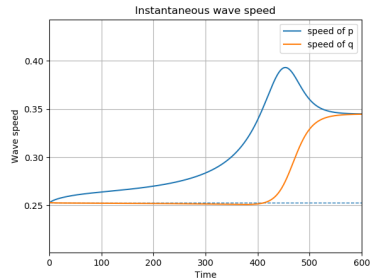
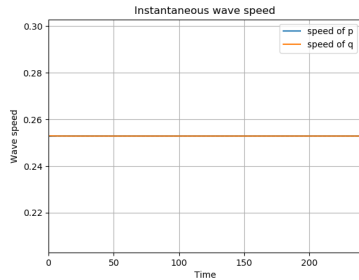
$$s_B = 0,$$

$$S_B = 0.1,$$

$$c_q = \frac{s_B}{\sqrt{S_B}} = 0$$

$$r = 0.01$$

Simulations: a condensed view



How are the speed computed?

- ▶ From the solutions $(p(x_n, t))_{0 \leq n \leq N}$ et $(q(x_n, t))_{0 \leq n \leq N}$
- ▶ Fit (at each timestep) the numerical solutions by a reference front, *i.e.* find $x_p(t)$ a minimizer of

$$\|p(x, t) - \frac{1}{1 + \exp(\sqrt{S_A}(x - x_p(t)))}\|_{\ell^2}^2 = \sum_{n=0}^N \left(p(x_n, t) - \frac{1}{1 + \exp(\sqrt{S_A}(x_n - x_p(t)))} \right)^2$$

and $x_q(t)$ a minimizer of

$$\|q(x, t) - \frac{1}{1 + \exp(\sqrt{S_B}(x - x_q(t)))}\|_{\ell^2}^2 = \sum_{n=0}^N \left(q(x_n, t) - \frac{1}{1 + \exp(\sqrt{S_B}(x_n - x_q(t)))} \right)^2$$

- ▶ Check the value of the errors for tolerance:
 $\varepsilon(x_p(t)) < 10^{-3}$ et $\varepsilon(x_q(t)) < 10^{-3}$
- ▶ Speeds are then defined by $c_p(t) = x'_p(t)$ et $c_q(t) = x'_q(t)$

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Generalized travelling waves in reaction–diffusion

- ▶ Heterogeneous domain: environment, medium of propagation...

$$\partial_t p = d(x)\Delta p + f(x, p)$$

- ▶ Transition front (Berestycki, Hamel, Matano 2009):
 1. global in time solution
 2. connecting two steady states
 3. whose width remains uniformly bounded
- ▶ Generalized travelling wave (Caputo, Sarels 2011):
 1. global in time solution
 2. close to a reference front \tilde{p}

$$p(x, t) \approx \tilde{p}\left(\frac{x - x_0(t)}{w}\right)$$

$$p(x, t) \approx \tilde{p}\left(\frac{x - x_0(t)}{w(t)}\right)$$

- ▶ Notions of **instantaneous** position (and width), consequently of **instantaneous speed**

Generalized travelling waves in reaction–diffusion

- ▶ Heterogeneous domain: environment, medium of propagation...

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- ▶ Notions of **instantaneous** position (and width), consequently of **instantaneous speed**



Generalized travelling waves in our case study

- ▶ Hypothesis on p

$$p(x, t) \approx \tilde{p} \left(\sqrt{S_A}(x - x_p(t)) \right)$$

- ▶ Hypothesis on q

$$q(x, t) \approx \tilde{q} \left(\sqrt{S_B}(x - x_q(t)) \right)$$

- ▶ 2 collective coordinates : x_p and x_q

- ▶ Here,

$$\tilde{p}(z) = \tilde{q}(z) = \frac{1}{1 + \exp(z)} =: k(z)$$

Case $S_A, S_B \ll r$: weak linkage disequilibrium

- ▶ With

$$\partial_t D \approx -Dr + 2\partial_x p \partial_x q + \partial_{xx}^2 D$$

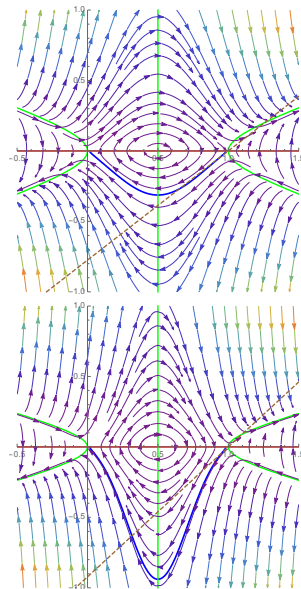
we expect D to stay close to

$$D \approx \frac{2}{r} \partial_x p \partial_x q$$

- ▶ Because $\partial_x p$ has order of magnitude $\sqrt{S_A}$ and $\partial_x q$ has order of magnitude $\sqrt{S_B}$,
→ weak linkage disequilibrium.

Case $S_A, S_B \ll r$: analytical results

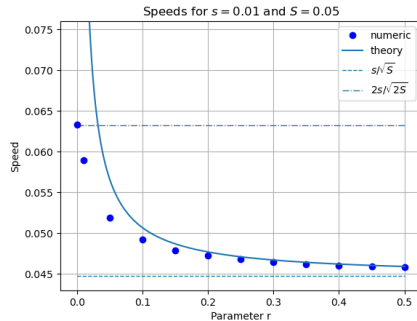
- ▶ For $s = 0$, existence (and construction) of a stationary solution (standing together)
- ▶ Stability of this solution
- ▶ For $s > 0$, existence of a travelling wave solution (travelling together)



Case $S_A, S_B \ll r$: theoretical results

- ▶ Initially stacked clines *with same parameters* stay stacked
- ▶ Acceleration of the front:

$$c^* \approx \frac{s}{\sqrt{S}} \left(1 + \frac{4S}{15r} \right)$$



Case $S_A, S_B \ll r$: reduced model I

- Suppose

$$p(x, t) = k(z_p) = k\left(\sqrt{S_A}(x - x_p(t))\right) \quad q(x, t) = k(z_q) = k\left(\sqrt{S_B}(x - x_q(t))\right)$$

we compute

$$\begin{aligned} \partial_t p &= -\sqrt{S_A} x'_p(t) k'(z_p) & \partial_x p &= \sqrt{S_A} k'(z_p) & \partial_{xx}^2 p &= S_A k''(z_p) \\ \partial_t q &= -\sqrt{S_B} x'_q(t) k'(z_q) & \partial_x q &= \sqrt{S_B} k'(z_q) & \partial_{xx}^2 q &= S_B k''(z_q) \end{aligned}$$

- Ansatz in the first two equations of $(\star_{p,q,D})$

$$\begin{cases} -\sqrt{S_A} x'_p(t) k'(z_p) = 2S_A R_\alpha(k(z_p)) + \frac{4S_B \sqrt{S_A S_B}}{r} \left(k(z_q) - \beta \right) k'(z_p) k'(z_q) + S_A k''(z_p) \\ -\sqrt{S_B} x'_q(t) k'(z_q) = 2S_B R_\beta(k(z_q)) + \frac{4S_A \sqrt{S_A S_B}}{r} \left(k(z_p) - \alpha \right) k'(z_q) k'(z_p) + S_B k''(z_q) \end{cases}$$

Case $S_A, S_B \ll r$: reduced model II

- Integrate over the spatial domain

$$\int_{-\infty}^{+\infty} k'(z) dz = -1, \quad \int_{-\infty}^{+\infty} k''(z) dz = 0, \quad \int_{-\infty}^{+\infty} R_\alpha(k(z)) dz = \frac{1-2\alpha}{2} = \frac{s_A}{2S_A}$$

- We get the following evolution equations

$$\left\{ \begin{array}{l} x'_p(t) = \frac{s_A}{\sqrt{S_A}} - \frac{2S_B^{1/2}(S_B - s_B)}{r} \int_{-\infty}^{+\infty} k'(z) k' \left(\sqrt{S_B}(x_p - x_q) + z \sqrt{\frac{S_B}{S_A}} \right) dz \\ \quad + \frac{4S_B^{3/2}}{r} \int_{-\infty}^{+\infty} k \left(\sqrt{S_B}(x_p - x_q) + z \sqrt{\frac{S_B}{S_A}} \right) k'(z) k' \left(\sqrt{S_B}(x_p - x_q) + z \sqrt{\frac{S_B}{S_A}} \right) dz \\ x'_q(t) = \frac{s_B}{\sqrt{S_B}} - \frac{2S_A^{1/2}(S_A - s_A)}{r} \int_{-\infty}^{+\infty} k'(z) k' \left(\sqrt{S_A}(x_q - x_p) + z \sqrt{\frac{S_A}{S_B}} \right) dz \\ \quad + \frac{4S_A^{3/2}}{r} \int_{-\infty}^{+\infty} k \left(\sqrt{S_A}(x_q - x_p) + z \sqrt{\frac{S_A}{S_B}} \right) k'(z) k' \left(\sqrt{S_A}(x_q - x_p) + z \sqrt{\frac{S_A}{S_B}} \right) dz \end{array} \right.$$

Case $S_A, S_B \ll r$: reduced model III

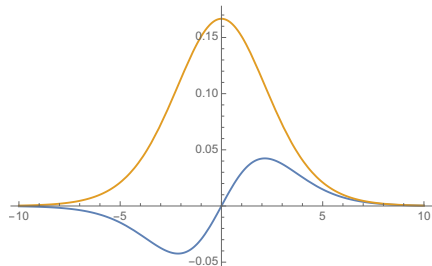
The system reads

$$\begin{cases} x'_p = c_p + \frac{S_B}{r} f_1(\sqrt{S_B}(x_p - x_q), S_B) \\ x'_q = c_q + \frac{S_A}{r} f_2(\sqrt{S_A}(x_q - x_p), S_A) \end{cases}$$

or

$$\theta' = c_p - c_q + F(\theta)$$

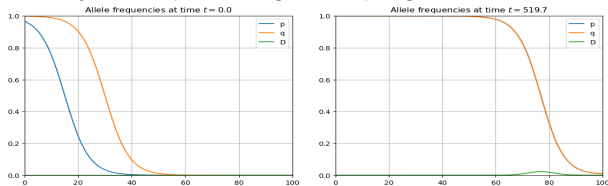
where $\theta = x_p - x_q$



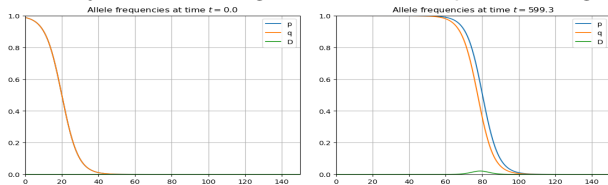
Terms f_1 in blue and f_2 in yellow

Case $S_A, S_B \ll r$: reduced model results

- Initially apart clines always end up stacking *or coupling*

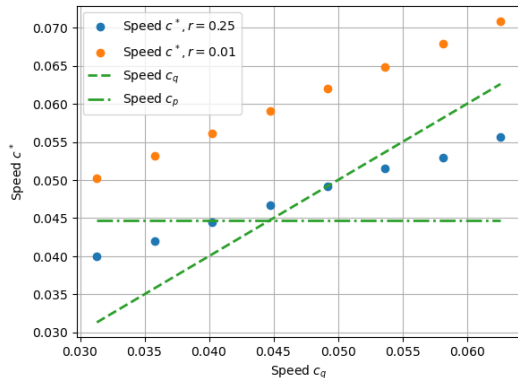


- Initially stacked clines *may start to diverge* but then end up stacked again *or coupled*



Case S_A, S_B, r arbitrary: numerical results and open questions

- ▶ Because the PDE system is more complicated, no reduced model
- ▶ According to numerical simulations:
 - ▶ More possible behaviors
 - ▶ Shift of an initially fixed cline



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- Model establishment

- Numerical simulations

- Generalized travelling waves

Opening: N underdominant loci in diploid individuals

One more locus adds a layer of complexity (again!)

We rewrite $(\star_{p,q,D})$ for 3 loci first, ignoring higher order linkage disequilibrium.

$$\left\{ \begin{array}{l} \partial_t p_A = 2S_A p_A(p_A - \alpha)(1 - p_A) + 2S_B (p_B - \beta)D_{AB} + 2S_C (p_C - \gamma)D_{AC} + \partial_{xx}^2 p_A \\ \partial_t p_B = 2S_B p_B(p_B - \beta)(1 - p_B) + 2S_A (p_A - \alpha)D_{AB} + 2S_C (p_C - \gamma)D_{BC} + \partial_{xx}^2 p_B \\ \partial_t p_C = 2S_C p_C(p_C - \alpha)(1 - p_C) + 2S_A (p_A - \alpha)D_{AC} + 2S_B (p_B - \beta)D_{BC} + \partial_{xx}^2 p_C \\ \partial_t D_{AB} = -D_{AB} \left(r + 4S_A(p_A - \alpha)(p_A - \frac{1}{2}) + 4S_B(p_B - \beta)(p_B - \frac{1}{2}) \right) + 2\partial_x p_A \partial_x p_B + \partial_{xx}^2 D_{AB} \\ \partial_t D_{AC} = -D_{AC} \left(r + 4S_A(p_A - \alpha)(p_A - \frac{1}{2}) + 4S_C(p_C - \gamma)(p_C - \frac{1}{2}) \right) + 2\partial_x p_A \partial_x p_C + \partial_{xx}^2 D_{AC} \\ \partial_t D_{BC} = -D_{BC} \left(r + 4S_B(p_B - \beta)(p_B - \frac{1}{2}) + 4S_C(p_C - \gamma)(p_C - \frac{1}{2}) \right) + 2\partial_x p_B \partial_x p_C + \partial_{xx}^2 D_{BC} \\ p_A(\cdot, 0) = p_{A0}(x) \quad p_B(\cdot, 0) = p_{B0}(x) \quad p_C(\cdot, 0) = p_{C0}(x) \\ D_{AB}(\cdot, 0) = 0 \quad D_{AC}(\cdot, 0) = 0 \quad D_{BC}(\cdot, 0) = 0 \end{array} \right.$$

We then make the hypothesis of *weak linkage disequilibrium*.

3 loci, two alleles, weak linkage disequilibrium

$$\begin{cases} x'_A = c_A & + \frac{S_B}{r} f_{AB}(\sqrt{S_B}(x_A - x_B), s_B) + \frac{S_C}{r} f_{AC}(\sqrt{S_C}(x_A - x_C), s_C) \\ x'_B = c_B & + \frac{S_A}{r} f_{BA}(\sqrt{S_A}(x_B - x_A), s_A) + \frac{S_C}{r} f_{BC}(\sqrt{S_C}(x_B - x_C), s_C) \\ x'_C = c_C & + \frac{S_A}{r} f_{CA}(\sqrt{S_A}(x_C - x_A), s_A) + \frac{S_B}{r} f_{CB}(\sqrt{S_C}(x_C - x_B), s_B) \end{cases}$$

- ▶ More intricate than for 2 loci
- ▶ Theoretically harder
- ▶ Numerical simulations

The case of N genes and the connection with the Kuramoto model

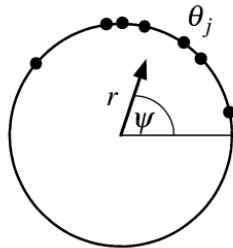
With N loci, at first order approximation, if $s_{A_i} = s_i$ and $S_{A_i} = S$, we get

$$x'_i = c_i + \frac{S}{r} \sum_{j=1}^N f_1(x_j - x_i, s_j) + \frac{1}{r} \sum_{j=1, j \neq i}^N f_2(x_j - x_i, s_j), \quad i \in \{1, \dots, N\}$$

- ▶ (Strong) similarity with the Kuramoto model

$$\theta'_i = \omega_i + \frac{K}{N} \sum_{j=1}^N \sin(\theta_j - \theta_i), \quad i \in \{1, \dots, N\}$$

- ▶ Differences : phase space, normalization constant $1/N$



$$re^{i\psi} = \frac{1}{N} \sum e^{i\theta_j}$$

Conclusion

- ▶ Interacting genetic incompatibilities
- ▶ Theorems are possible in some restrictive situations
- ▶ Generalized travelling waves allow to go a step further
 1. Numerically
 2. Conceptually
- ▶ System of N clines \rightarrow system of N points!

Thank you for your attention!

Conclusion

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Thank you for your attention!